

Feynman Integrals at Spectral Speed

A fast, stable and adaptive approach to multi-scale calculations in particle physics

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1 • INTRODUCTION

Multi-loop integrals sharpen tests of the Standard Model

Higher-order quantum corrections are essential for precision collider predictions. Multi-loop Feynman integrals reduce theoretical uncertainty, enabling stringent tests of the Standard Model and increasing sensitivity to possible new physics.

2 • THE CHALLENGE

Complexity grows with scales, systems and singularities

Phenomenology requires repeated evaluation of large master-integral systems across a singular, high-dimensional phase space.

1

TRAVERSE PHASE SPACE QUICKLY

Low cost for repeated point-to-point evaluation.

2

BE ROBUST IN THE PHYSICAL REGION

Handle physical thresholds and spurious alphabet singularities.

3

HANDLE LARGE COUPLED SYSTEMS

Remain efficient as the number of master integrals grows.

4

HANDLE MANY KINEMATIC SCALES

Remain practical as the number of independent invariants grows.

5

REQUIRE MINIMAL ANALYTIC INPUT

Given the DEs, regional boundary values suffice—no closed-form solution is required.

Evaluate only the phase-space points the observable needs—quickly, accurately and robustly throughout the physical region.

SELECTED REFERENCES

- [1] J. M. Henn, Multiloop integrals in dimensional regularization made simple, Phys. Rev. Lett. 110 (2013) 251601, [1304.1806].
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[3] Z. Battles and L. N. Trefethen, An extension of MATLAB to continuous functions and operators, SIAM Journal on Scientific Computing 25 (2004) 1743–1770, [https://doi.org/10.1137/S1064827503430126].
[4] J. L. Aurentz and L. N. Trefethen, Chopping a Chebyshev Series, arXiv e-prints (Dec., 2015) arXiv:1512.01803, [1512.01803].

3 • METHOD

Canonical equations transport the solution

Boundary data are evolved through kinematic space using a closed first-order system.

THE USEFUL CASE — CANONICAL ϵ -FORM

Choose a basis in which the regulator dependence factorises [1].

$$d\vec{I} = \epsilon \sum_j A_j \, d\log W_j(s) \, \vec{I}$$

ϵ factor
dimensional regulator

A_j matrices
constant rational entries

W_j letters
algebraic kinematic functions

4 • CENTRAL IDEA

Why Chebyshev series?

1

Fast convergence

Analytic regions are captured accurately with relatively few coefficients.

2

One series per interval

A single approximation represents the function throughout each path segment.

3

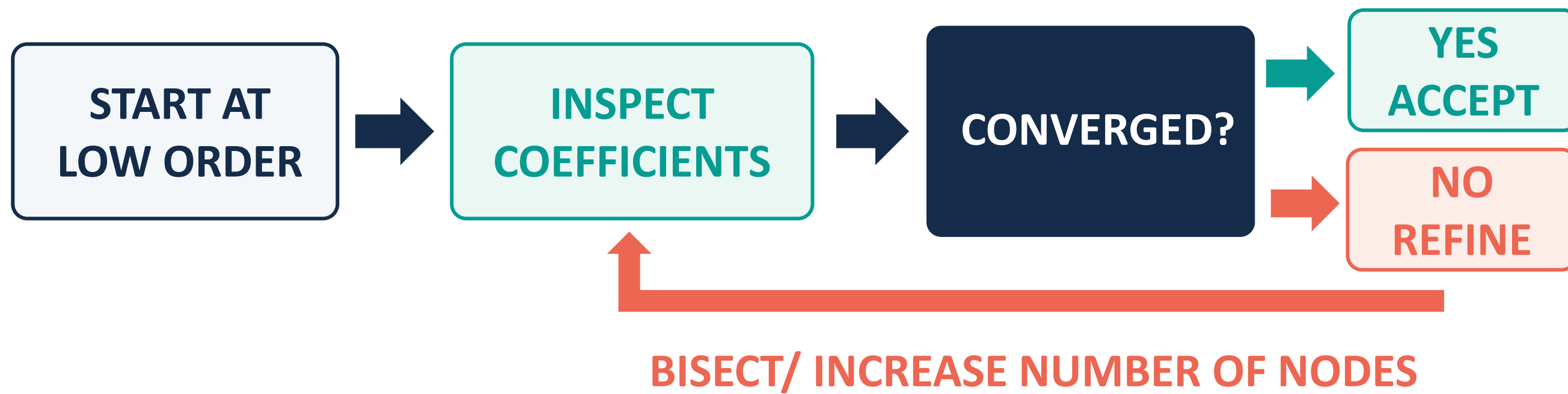
Cheap to reuse

Evaluation and integration become fast once the coefficients are known.

5 • ADAPTIVE ALGORITHM

Coefficients guide the computation

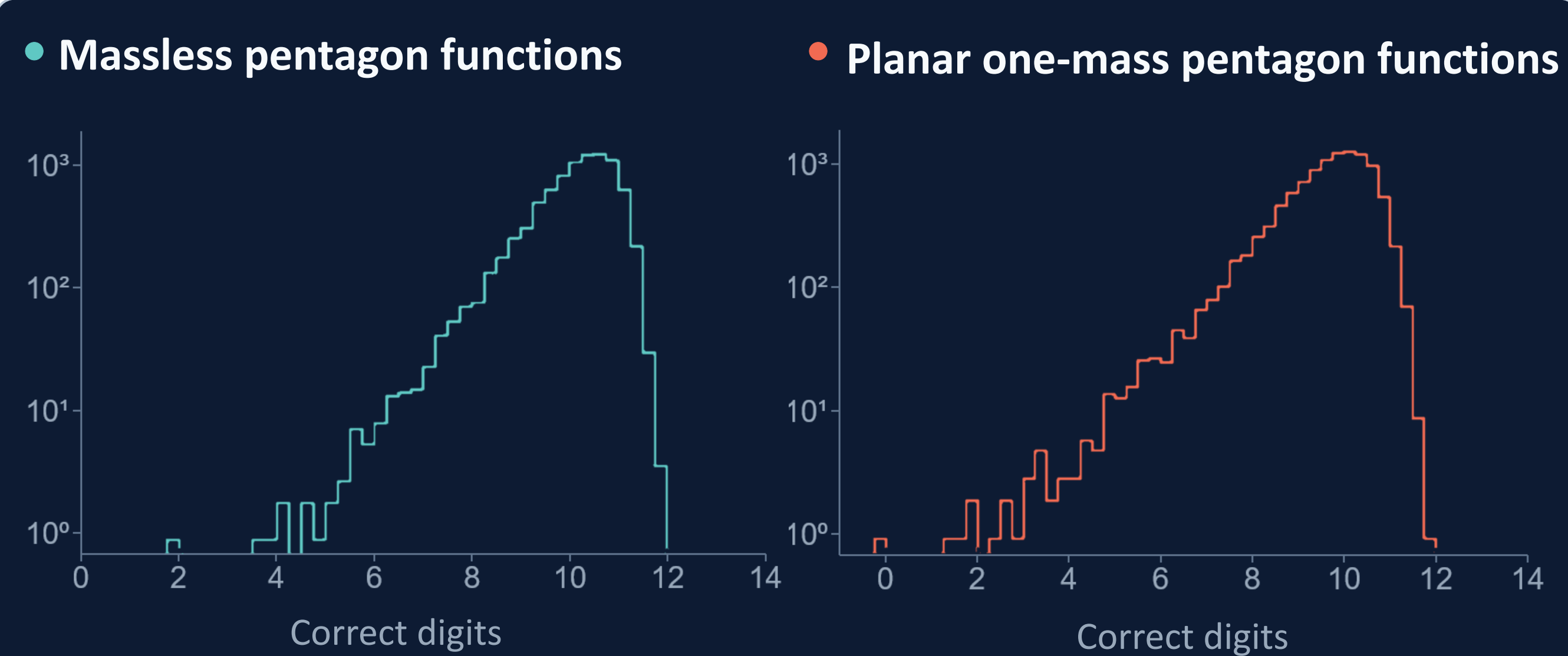
Adaptive sampling redirects computation toward regions with slower convergence [2-4].



The approximation stays light in smooth regions and concentrates samples near difficult structures.

6 • RESULTS

Agreement reaches about 10 correct digits



Evaluation time per point

MEDIAN

MEAN

MAX

• Massless pentagon

0,35 s

0,56 s

6,5 s

• Planar one-mass

1,2 s

1,45 s

10,7 s

≈10

correct digits

<2 s

median time

10 000

phase space points

7 • Conclusion and Future Work



SCALABLE

Fast, reusable approximations for large systems



PHYSICAL

Validated in physical relevant regions.



COMPETITIVE

Agreement with existing methods

Apply the framework to cutting-edge two-loop six-point massless integrals, building on recent results.

TAKE-HOME MESSAGE

Chebyshev series provide fast, reusable approximations.

The coefficients diagnose convergence, allowing adaptivity to focus computation only where the analytic structure makes it necessary.